A Simple Nonmydriatic Self-Retinal Imaging Procedure Using a Kowa Genesis-D Hand-Held Digital Fundus Camera

Ugur Ozerdem
La Jolla Bioengineering Institute, La Jolla, Calif., USA

Blood and tissue fluid shifts associated with weightlessness offer unique opportunities to study perturbations in vascular transmural pressure changes and associated edema in the upper body (face, eyelids, vocal cords, brain) during space explorations. In a microgravity (or simulated microgravity) environment capillary pressure (Pc) increases in the head and neck. The reason for the increase of Pc in the upper body is because hydrostatic fluid pressure within the vasculature behaves like a vertical column of water and is affected by gravity. The difference between Pc and interstitial fluid pressure is greater in magnitude in the upper body parts during space flight [4, 5]. An increase in Pc in the upper body counteracts interstitial fluid pressure and therefore increases net transcapillary fluid leakage and edema.

High-resolution, hand-held digital fundus cameras have recently become available for retinal imaging. Kowa Genesis-D is a compact, lightweight, hand-held fundus camera. This system is equipped with a built-in digital camera which provides 2.0 million pixels of resolution and an LCD monitor screen. In this brief report we describe a simple, nonmydriatic, retinal self-imaging technique using a Kowa Genesis-D hand-held digital camera and a Black and Decker laser level. This simple technique will be useful to clinical physiologists conducting microgravity research, as well as for the studies of high-altitude medicine and aviation physiology.
Materials, Methods and Results

A Kowa Genesis-D fundus camera (serial No. 1501500288, Tokyo, Japan) was used as a hand-held digital fundus camera. The weight of the camera is 1,070 g and the dimensions are 74.5 mm (width) \( \times \) 197 mm (depth) \( \times \) 278.5 mm (height). This camera has approximately 30° of horizontal angle of view. Since the angular distance between fovea and optic nerve is approximately 15° [6], a 7.5° adduction of the eye was calculated to translate to a 7.5° temporal displacement of the macula off the optical axis. A simple laser level (Black and Decker, DL220S, Towson, Md., USA) was used for aligning the eye 7.5° nasally (adduction) so that both optic nerve head and macula were approximately located in the center of the digital image frame obtained with this camera. The laser streak was projected onto a wall in a darkroom 100 cm away from the right eye. The wall was viewed through the objective lens of the camera which functioned as an ocular eyepiece for this imaging technique. The eyes were dark-adapted for 5 min in the dark room. The forehead rest of the camera was placed on the frontal bone. The original eyepiece of the camera served as an objective lens to view the laser streak on the wall (fig. 1a). The laser streak was then shifted on the wall to project 13 cm off the optical axis, which was represented by the triangular notch of the picture frame in this particular camera. The 13-cm horizontal displacement of laser streak was calculated by using basic trigonometry (100 cm \( \times \) \( \tan \) 7.5° = 13 cm). The right eye then gazed at the laser streak on the wall while the camera position on the forehead was kept constant. The shutter on the camera handle was switched on by using the right thumb to capture the image (fig. 1b). The entire procedure, including 5 min of the dark adaptation period, took less than 7 min. The JPEG image obtained was of sufficient quality to apply NIH image J 1.39t image analysis software to quantify the relative size of major vascular structures (retinal arteries and veins) representative of central nervous system vasculature. A practical application of this technique in a simulated microgravity model with 6° head-down tilt is shown in figure 2.

Discussion

In the late 1970s, Kowa RC-2 cameras were modified successfully by the addition of custom-made bite plates to position the camera, attaching cross-hair targets, and a focusing light in the view finder (ocular eyepiece) [7]. Our technique uses a more advanced camera which requires only a miniature external laser level (Black and Decker, DL220S), and no modifications to the camera hardware. This easy-to-apply, nonmydriatic procedure can be used by crew members without any compromising vision or sacrificing safety in situations where payload and imaging time are limited (such as spacecraft, aircraft, and tent of a mountaineer physiologist). The compactness of this hand-held fundus camera coupled with the simplicity of the procedure we describe makes it possible for anyone who can use a standard digital camera to perform retinal self-imaging in a darkroom with a wall in 100 cm distance. Therefore, changes in central nervous system (ret-
in microgravity research. a The same image as in figure 1b was compared with the self-fundus photograph obtained during bed-rest, after 45 min of supine bedrest with 6° of head-down tilt. Caliber of the superior temporal retinal artery (stra) and superior temporal retinal vein (strv) in the same anatomic location (arrows) was measured with NIH image J 1.39t image analysis software in pixels. The measurement reveals a wall diameter of 25,554 and 29,120 pixels for stra and strv, respectively, in standing position. b Following 45 min of supine bedrest with 6° of head-down tilt (HDT) a reduction of vascular caliber to 24,498 and 27,893 pixels was noted for stra and strv, respectively.

The neurosensory retina is an embryological derivative of the diencephalon, and is thus part of the central nervous system, as is the optic nerve. The retinal artery is a branch of ophthalmic artery, which is the first branch of internal carotid artery. Using the simple, retinal self-imaging procedure and equipment described herein, we expect that changes in central nervous system vessels can be studied more extensively thereby contributing significantly to the fields of microgravity research, aviation physiology and in high-altitude medicine.

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References